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RIGOROUS RESULTS ON A TIME-DEPENDENT
INHOMOGENEOUS COULOMB GAS PROBLEM

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Rigorous results on a time-dependent inhomogeneous Coulomb gas problem^{*)}

by

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ABSTRACT

We report results obtained by rigorous analysis of a nonlinear differential equation for the electron density n_e in a specific type of electrical discharge. The problem is essentially two-dimensional. We discuss in particular (i) the escape of electrons to infinity above a critical temperature; and (ii) the boundary layer exhibited by n_e near zero temperature.

KEY WORDS & PHRASES: *singularly perturbed nonlinear two-point boundary value problem; nonlinear parabolic equation degenerate at the origin in one space dimension; Coulomb gas; pre-break-down discharge in an ionized gas between two electrodes*

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In a filamentary discharge studied by Marode et al. [1,2] electrons and ions are produced with number densities n_e and n_i , respectively. The charged particles move in a background of neutrals. The discharge area is cylindrical and has its radial dimension much smaller than its longitudinal dimension. Since to a good approximation the physical situation is cylindrically symmetric, it suffices to consider a two-dimensional cross section perpendicular to the cylinder axis, in which all quantities involved are functions only of the distance r to the axis. As the ions are heavy and slow, $n_i(r, t) \equiv n_i(r)$ may be regarded as fixed on the time scale of interest. For the density $n_e(r, t)$ Marode et al. [3] use the following three equations:

(i) Coulomb's law

$$\frac{1}{r} \frac{\partial}{\partial r} rE(r, t) = 4\pi e[n_i(r) - n_e(r, t)] \quad (1)$$

where E is the electric field and $-e$ the electron charge;

(ii) a constitutive equation for the current density $j(r)$, consisting of a drift term and a diffusion term,

$$j(r, t) = e\mu n_e(r, t)E(r, t) + eD \frac{\partial n_e(r, t)}{\partial r} \quad (2)$$

where μ is the electron mobility and D the diffusion constant; and

(iii) the continuity equation

$$e \frac{\partial n_e(r, t)}{\partial t} = \frac{1}{r} \frac{\partial}{\partial r} rj(r, t). \quad (3)$$

Both E and j are radially directed.

From Eqs. (1) - (3) a nonlinear partial differential equation for a single function can be derived. To this end we set [4]

$$u(x, t) = \int_0^{\sqrt{x}} \rho n_e(\rho, t) d\rho, \quad (4a)$$

$$g(x) = \int_0^{\sqrt{x}} \rho n_i(\rho) d\rho. \quad (4b)$$

Upon employing for the diffusion constant the Einstein relation $D = k_B T \mu / e$ (where k_B is Boltzmann's constant and T the electron temperature), putting $\epsilon = k_B T / (2\pi e^2)$, and absorbing a factor $8\pi\mu e$ in the time scale we deduce that u satisfies

$$u_t = \epsilon x u_{xx} + (g-u)u_x, \quad (5)$$

$$u(0,t) = 0. \quad (6)$$

By its definition $g(0) = 0$. Typically, as r increases, $n_i(r)$ rapidly falls off to zero, and hence $g(x)$ attains a limit value $g(\infty)$. The nonlinear term in Eq. (5) represents the interaction between the electrons. Without it, this equation would reduce to a linear one studied by McCauley [5] and describing the Brownian motion of a pair of opposite two-dimensional charges in each other's field. As it stands, Eq. (5) is rather reminiscent of the nonlinear equations occurring in the Thomas-Fermi theory of the atom (see, e.g., ref. [6]).

In the experimental situation that we are describing the total charge in the discharge area is positive and conserved in time. This is expressed by

$$u(\infty, t) = N_e \quad \text{for } 0 \leq t < \infty \quad (7)$$

with $0 \leq N_e < g(\infty)$. One of the authors has investigated [4,7,8], by rigorous mathematical methods, the solution of Eqs. (5) and (6) for a given initial distribution $u(x,0) = u_0(x)$ and subject to condition (7) on the total charge. Here we present the main results in physical language.

1. We take g concave and in $C^2([0, \infty))$. Then at given ϵ (i.e. at given temperature), there exists [4] a unique stationary solution $u_{st}(x)$ if the total number of electrons N_e is such that $N_e \leq g(\infty) - \epsilon$. In particular, when $\epsilon \geq g(\infty)$, thermal motion prevents any electrons to be bound to the fixed ionic background. The existence of such a critical temperature is characteristic of two-dimensional Coulomb systems [9]. The main mathematical tools in treating the stationary problem are maximum principle arguments and the construction of upper and lower solutions.

2. The solution u_{st} , when it exists, has the following properties [4].

(i) It belongs to $C^2([0, \infty))$. It is strictly increasing, concave, and bounded from above by the function $\min(g(x), N_e)$. As $x \rightarrow \infty$, $u_{st}(x)$ approaches its limiting value N_e at least fast enough so that

$$n_e(r) \leq n_e(r_1) \left(\frac{r^2}{x_1^2} \right)^{-\frac{1}{\epsilon} [g(x_1) - N_e]}, \quad r \rightarrow \infty, \quad (8)$$

where $r_1^2 \equiv x_1^2 > 0$ is arbitrary. Such power law decay is again typical of Coulomb systems in two dimensions.

(ii) As $\epsilon \downarrow 0$, $u_{st}(x)$ converges to $\min(g(x), N_e)$ uniformly on $[0, \infty)$, and we have for the zero temperature limit of the electron density

$$\lim_{\epsilon \downarrow 0} n_e(r) = \begin{cases} n_i(r) & r < r_0 \\ 0 & r > r_0 \end{cases} \quad (9)$$

where the critical radius r_0 is defined by the relation $g(r_0) = N_e$.

At small ϵ there is a transition layer of width $\sim \epsilon^{\frac{1}{2}}$, located at r_0 , analogous to a Debye shielding length [3]. A uniformly valid approximate stationary solution for $\epsilon \ll 1$ is given in [4]. It is obtained by the method of matched asymptotic expansions.

3. We consider now the time evolution problem of Eqs. (5) and (6).

Suppose that the initial condition u_0 is sufficiently smooth, nondecreasing, with bounded derivative, and with $u_0(0) = 0$ and $u_0(\infty) = N_e$.

Mathematically one has to find a way to deal with the degeneracy of the parabolic equation (5) in the origin. In [7] this is done via a sequence of regularized problems. The following is shown.

(i) The time evolution problem has a unique solution $u(x, t)$ such that u and u_x are bounded. In fact it satisfies $0 \leq u(x, t) \leq N_e$, it is non-decreasing in x for all t , and for each $t \geq 0$ we have $u(\infty, t) = N_e$.

(ii) In order to discuss the behavior of $u(x,t)$ as $t \rightarrow \infty$ we consider the function \bar{u}_{st} which satisfies the steady state equation and has boundary values $\bar{u}_{st}(0) = 0$ and

$$\bar{u}_{st}(\infty) = \begin{cases} N_e & \text{if } N_e \leq g(\infty) - \epsilon \\ g(\infty) - \epsilon & \text{if } 0 < g(\infty) - \epsilon < N_e \\ 0 & \text{otherwise} \end{cases} \quad \begin{matrix} (10a) \\ (10b) \\ (10c) \end{matrix}$$

We know from section 1 that \bar{u}_{st} exists and is unique. In particular, in the case of Eq. (10c), $\bar{u}_{st}(x) \equiv 0$. Our result is that the solution $u(x,t)$ of the evolution problem converges to $\bar{u}_{st}(x)$ as $t \rightarrow \infty$, uniformly on all compact subsets of $[0, \infty)$; in the case of Eq. (10a) the convergence is actually uniform on $[0, \infty)$. The proofs are based upon the use of upper and lower solutions of the stationary problem and on a comparison theorem. Thus we have proved that all the electrons stay attached to the ions for $t \leq \infty$ at temperatures such that $\epsilon \leq g(\infty) - N_e$ (case (10a)). If the temperature rises above this critical value, then some of the electrons diffuse away to infinity (case (10b)), and if it rises above a second critical value, viz. $\epsilon = g(\infty)$, then all electrons escape to infinity (case (10c)).

(iii) For the case of Eq. (10a) (with the inequality strictly satisfied) we have derived results about the rate of convergence of u to \bar{u}_{st} . Let the initial state have the property that $N_e - u_0(x) \leq N_e (x_1/x)^\nu$ for some $x_1, \nu > 0$ satisfying $\epsilon \leq (\nu+1)^{-1} [g(x_1) - N_e]$. Then $u(x,t)$ converges to $\bar{u}_{st}(x)$ at least as fast as $t^{-1/(2p)}$ with $p = [1/\nu] + 1$, for all finite x . Furthermore, if $\nu > 1$ and $\epsilon < \frac{1}{2}[g(\infty) - N_e]$, then u converges to \bar{u}_{st} at least as fast as $t^{-\frac{1}{2}}$.

4. *Negative regions in the background charge density.* We have considered an interesting modification of the above problem obtained by also allowing negative ions to be present in the fixed background [8].

This leads to a function g which can assume minima and maxima. We studied the stationary state on a bounded domain $[0, R]$ with boundary condition $u_{st}(R) = N_e$. For non-monotone g it is nontrivial to find the zero temperature ($\epsilon \rightarrow 0$) limit of $u_{st}(x)$ (and thus of $n_e(r)$), since the solution of the reduced differential equation (i.e. the one obtained by setting $\epsilon = 0$) is no longer unique. To solve this problem we observe that for $\epsilon > 0$ the solution $u_{st}(x; \epsilon)$ minimizes the free energy functional

$$F_\varepsilon[u] = \varepsilon \int_0^R u_x \ln u_x dx + \frac{1}{2} \int_0^R \frac{(g-u)^2}{x} dx, \quad (11)$$

which is readily recognized as the sum of an entropy and an electrostatic energy term.

In [8] two alternative methods were used to study the minimization of F_ε : one based on the theory of maximal monotone operators and one on duality theory. Both yield

$$\lim_{\varepsilon \rightarrow 0} u_{st}(x; \varepsilon) = \inf_{0 \leq u \leq N_e, u' \geq 0} \frac{1}{2} \int_0^R \frac{(g-u)^2}{x} dx, \quad (12)$$

i.e. the limit solution of the differential equation is the physically expected minimum energy configuration. The function $u_{st}(x; 0)$ is continuous [10] and can be characterized as follows: there exist intervals $[a_1, b_1]$, $[a_2, b_2], \dots, [a_s, b_s]$, $s \geq 0$, where $u_{st}(x; 0)$ takes constant values c_1, c_2, \dots, c_s , respectively, and where, therefore, $n_e(r) = 0$. Outside those intervals $u_{st}(x; 0) = g(x)$. The constants a_i, b_i, c_i , $i = 1, 2, \dots, s$, can be shown, finally, to be uniquely determined by the set of implicit inequalities

$$\left. \begin{aligned} \int_{a_i}^{b_i} \frac{c_i - g(\xi)}{\xi} d\xi &\geq 0 && \text{if } c_i \neq N_e \\ \int_{a_i}^{b_i} \frac{c_i - g(\xi)}{\xi} d\xi &\leq 0 && \text{if } c_i \neq 0 \end{aligned} \right\} \text{ for all } x \in [a_i, b_i], i=1, 2, \dots, s. \quad (13a)$$

$$\left. \begin{aligned} \int_{a_i}^{b_i} \frac{c_i - g(\xi)}{\xi} d\xi &\geq 0 && \text{if } c_i \neq N_e \\ \int_{a_i}^{b_i} \frac{c_i - g(\xi)}{\xi} d\xi &\leq 0 && \text{if } c_i \neq 0 \end{aligned} \right\} \text{ for all } x \in [a_i, b_i], i=1, 2, \dots, s. \quad (13b)$$

To verify this characterization of $u_{st}(x; 0)$, one checks [8] that this function satisfies a variational inequality related to the minimization problem (12). In particular, if $0 < c_i < N_e$, we have the equal area construction $\int_{a_i}^{b_i} (c_i - g(\xi)) \xi^{-1} d\xi = 0$. The interpretation is that the points $x = a_i$ and $x = b_i$ are at equal potential and separated by a potential barrier. Eqs. (13) may serve as the basis for a numerical algorithm to compute a_i, b_i, c_i .

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